

# Getting and Losing Traction

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# Introduction

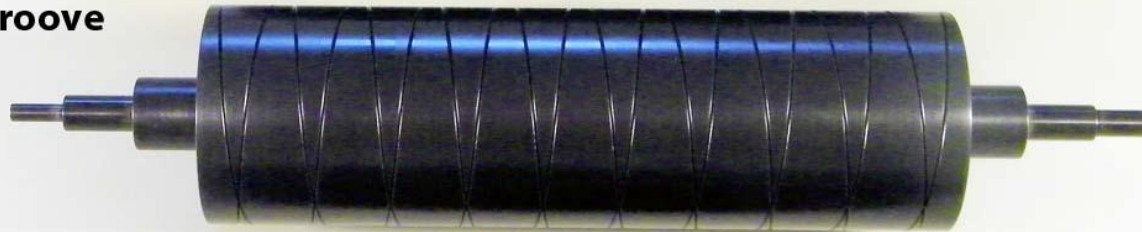
- Assuming good traction ... ??? How many times have you read that?
- Because of air lubrication, the web begins to lose traction *as soon as it starts moving*.
- A lot is known about air lubrication. There are even some very good theoretical modeling tools.
  - But the emphasis here will not be on modeling.
  - It will be on getting a sense of how things go when you change something.
- Focus will be on comparisons of tests of three different types of rollers:
  - A standard roller
  - A spiral groove roller
  - A microgroove roller

# The rollers

**Standard**



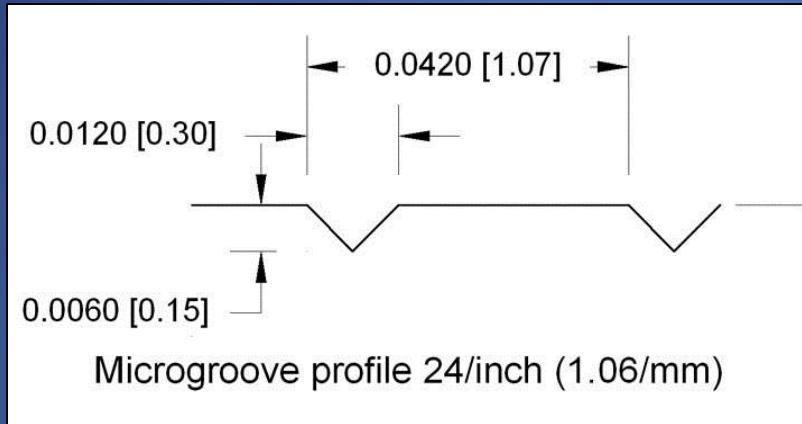
**Spiral groove**



**Microgroove**

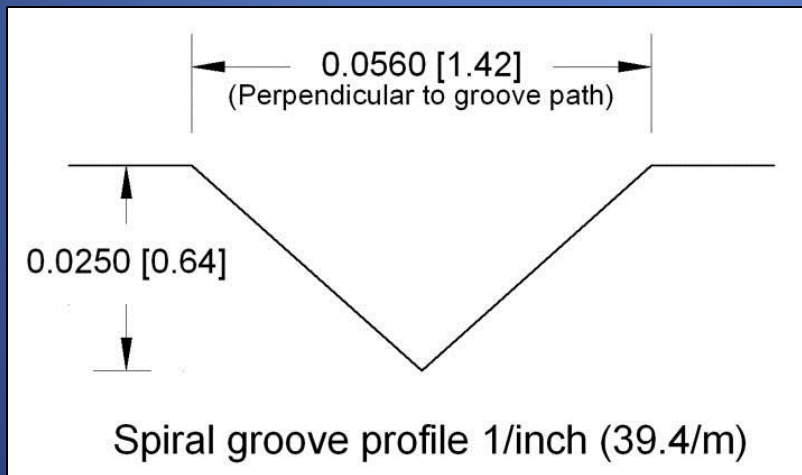


# Groove geometries



Microgroove is 2.7 inch (69 mm) wide in the circumferential direction.

Spiral groove is 0.53 inch (13.5 mm) wide in the circumferential direction.



# Thanks

- The grooved rollers are commercially available designs which were generously donated by Webex (thank you Pete Eggen).
  - Historical note: The Webex microgroove design was developed in cooperation with 3M many years ago (thank you Tim Walker).
- The web used throughout the tests is Tedlar donated by DuPont (thank you John Wysokowski).

# The plan for what follows

- Description of the test machine
  - Schematic
  - Sensors
  - Drive
  - Brake and torque measurement
  - Bearing friction

# The plan for what follows

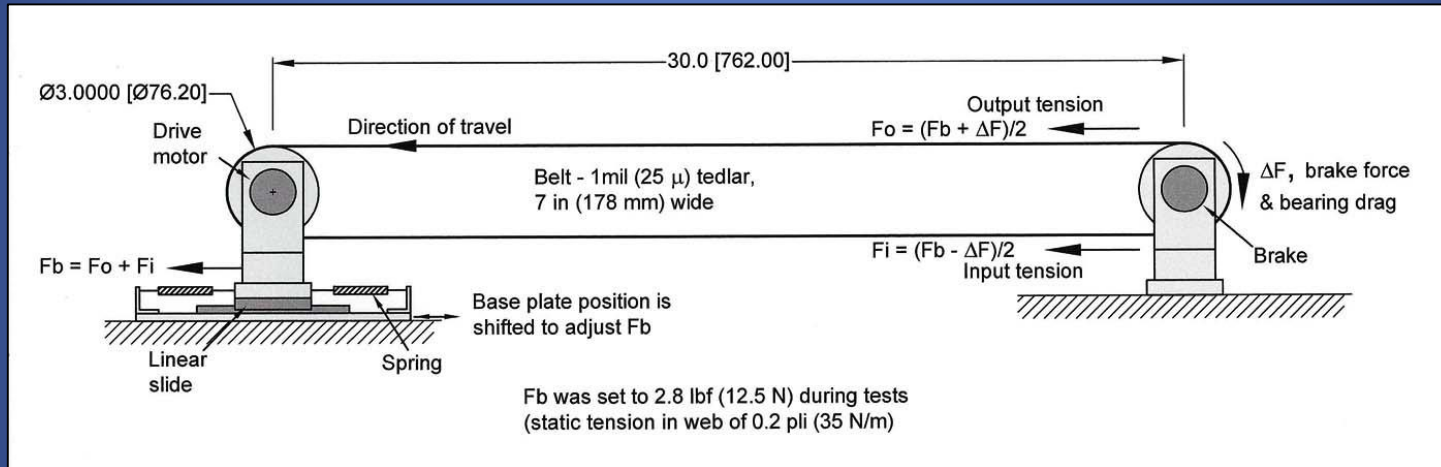
- An explanation of what is going on:
  - Effect of friction on traction
    - Capstan behavior
  - Air lubrication
    - How the entrained air behaves
  - Interaction of the air film with web and roller surfaces
  - Venting techniques
    - Annular grooves

# The plan for what follows

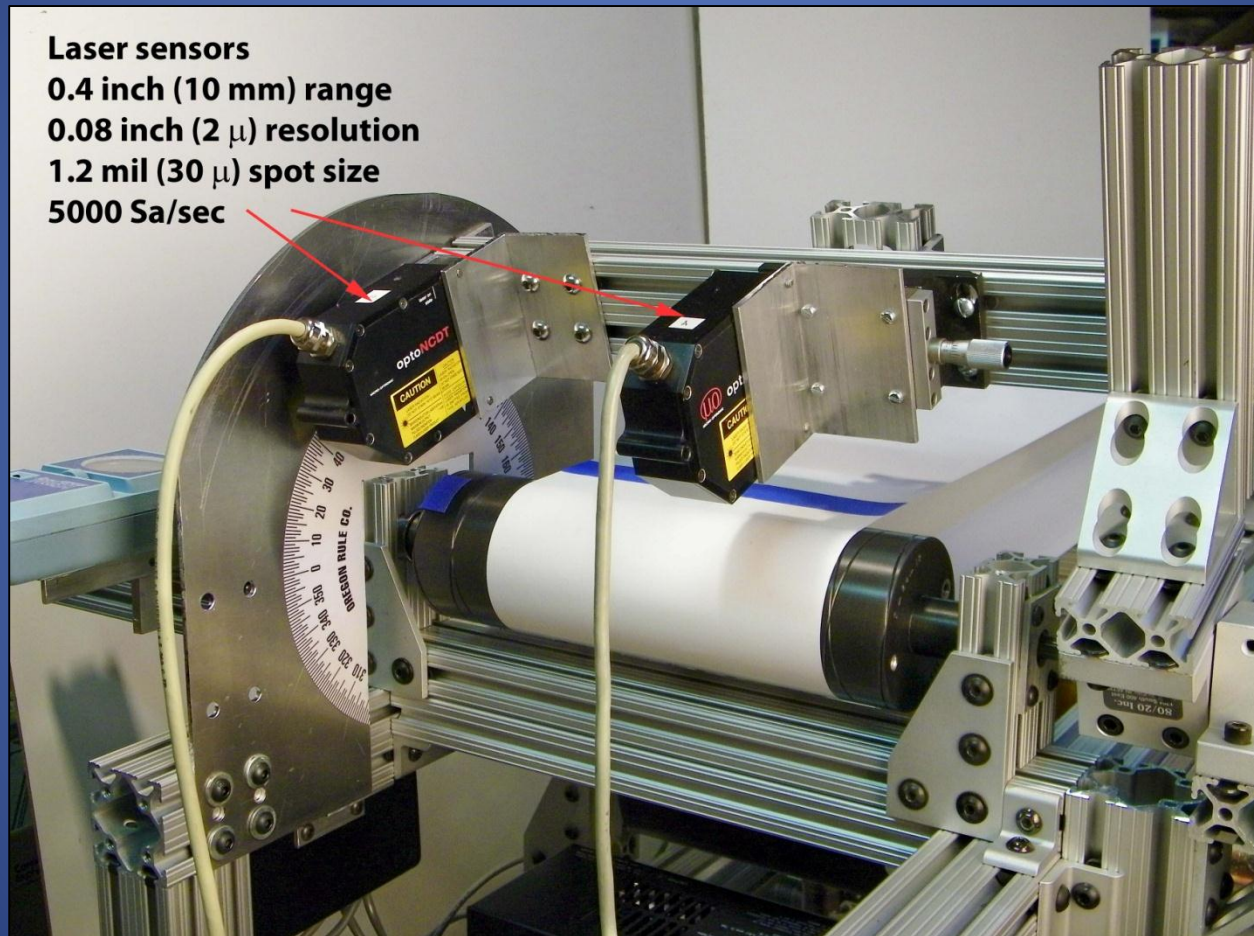
- Test results
  - Standard roller
  - Microgroove roller
  - Spiral groove roller
- For each type we will see:
  - The speed at which the web begins slipping on the roller
  - How the effective coefficient of friction between the web and roller changes with speed.



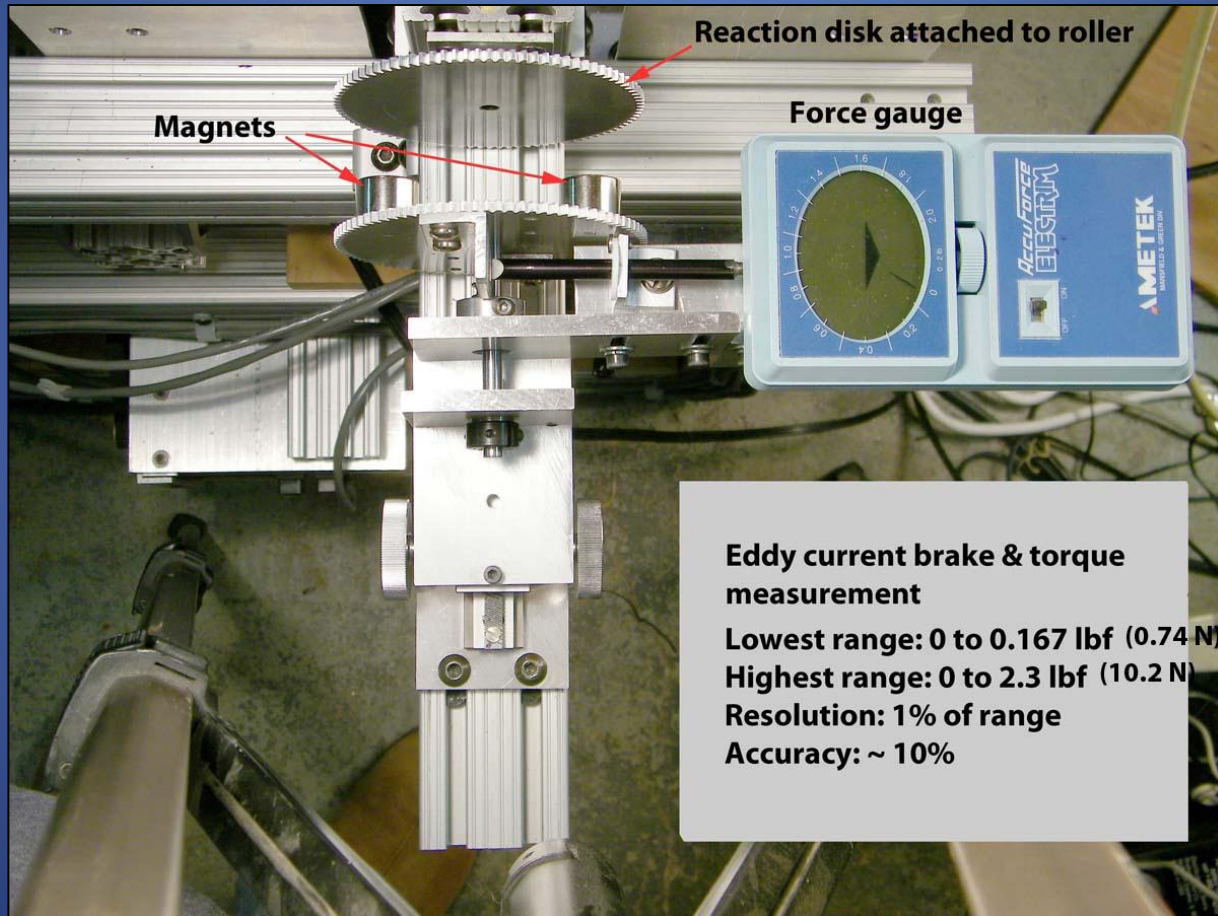
# The machine



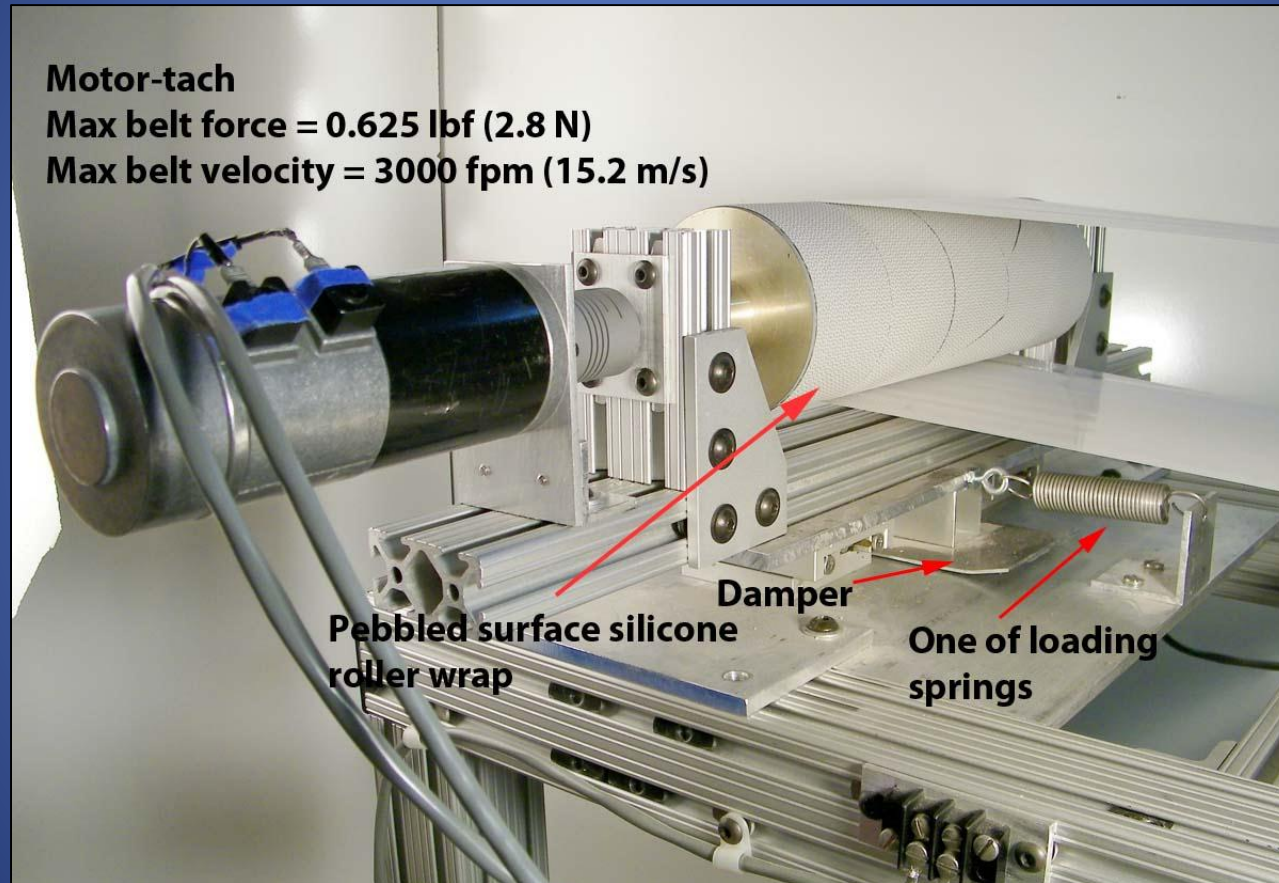
# The measurement end



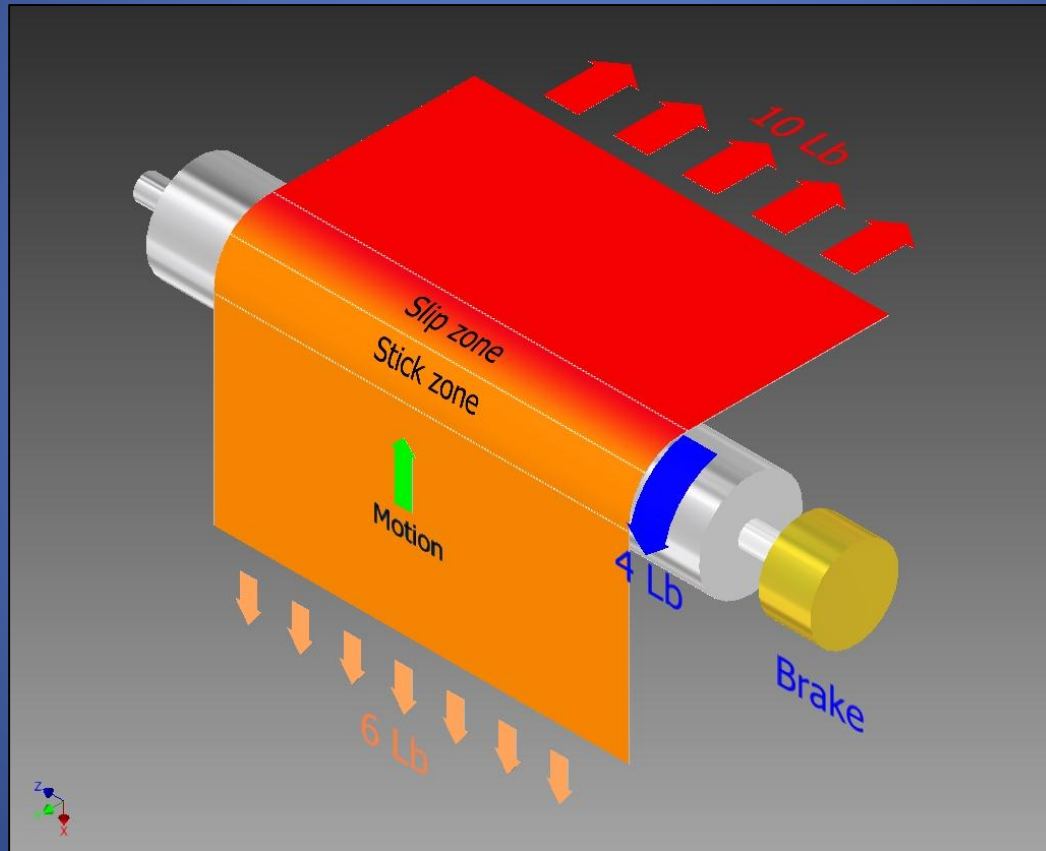
# Eddy current brake & torque measurement



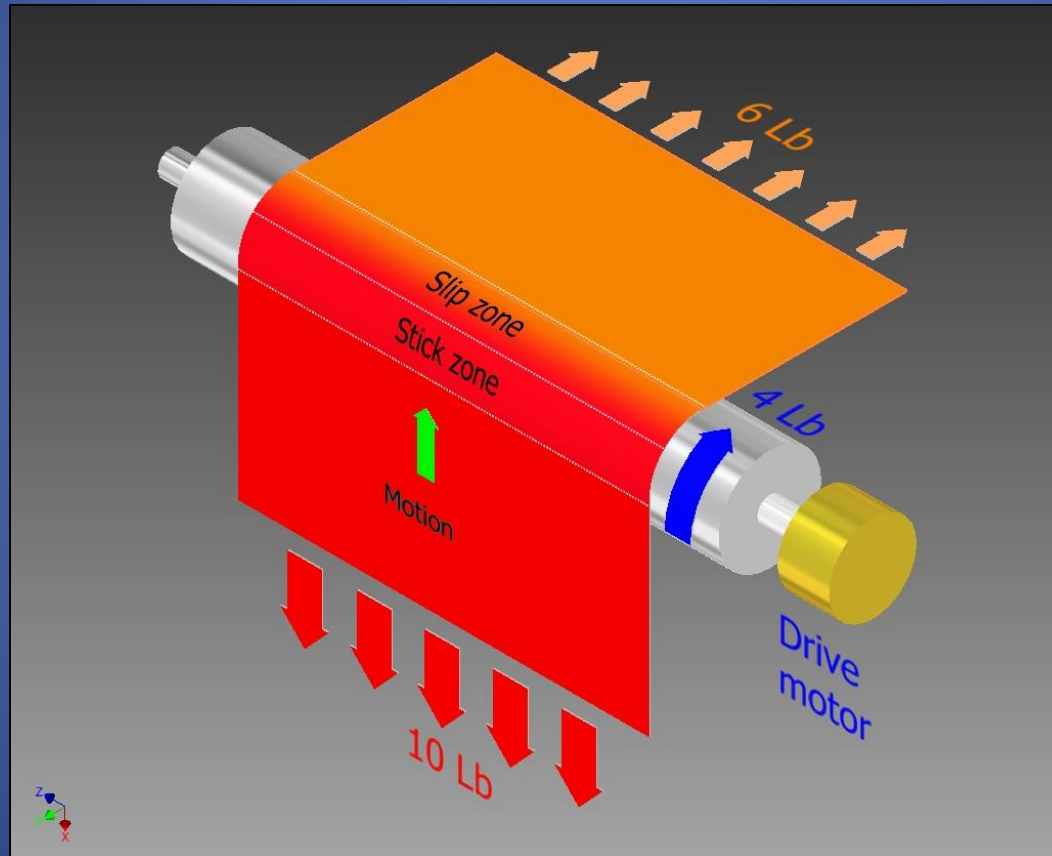
# The drive end



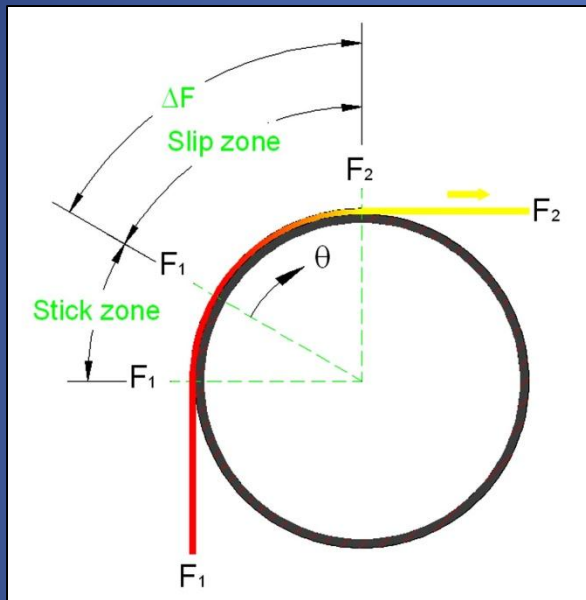
# Stick and microslip zones - braking



# Stick and microslip zones - driving



# Capstan equation



Tension is transferred between the roller and the web in the microslip zone.

[Back to friction vs speed](#)

$$\frac{F_2}{F_1} = e^{f\theta}$$

If we know:

$F_1$ ,  $F_2$  and  $\theta$

$f$ , the coefficient of friction, can be calculated

$$f = \frac{1}{\theta} \ln \frac{F_2}{F_1}$$

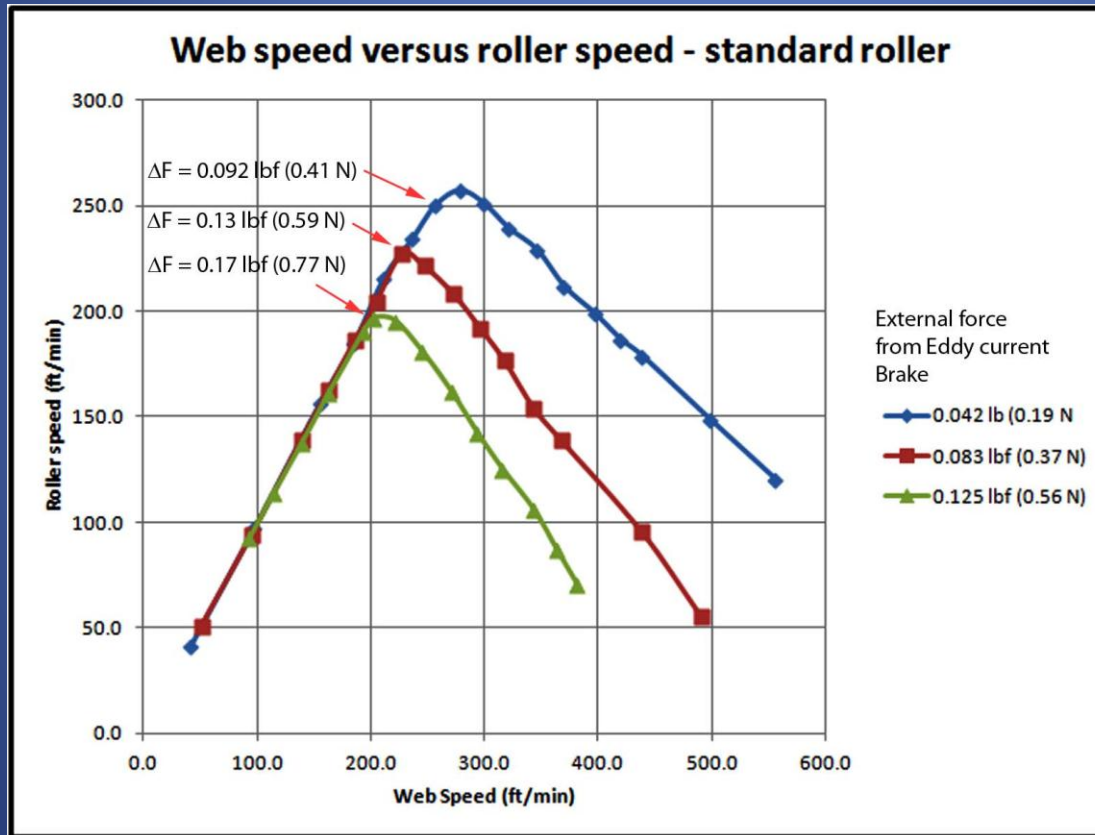
Or if we know:

$F_1$ ,  $F_2$  and  $f$

$\theta$  can be calculated

$$\theta = \frac{1}{f} \ln \frac{F_2}{F_1}$$

# Web speed vs Roller speed (slip curves) standard roller



These slip curves show web speed vs. roller speed.

As braking torque increases the breakaway speed decreases.

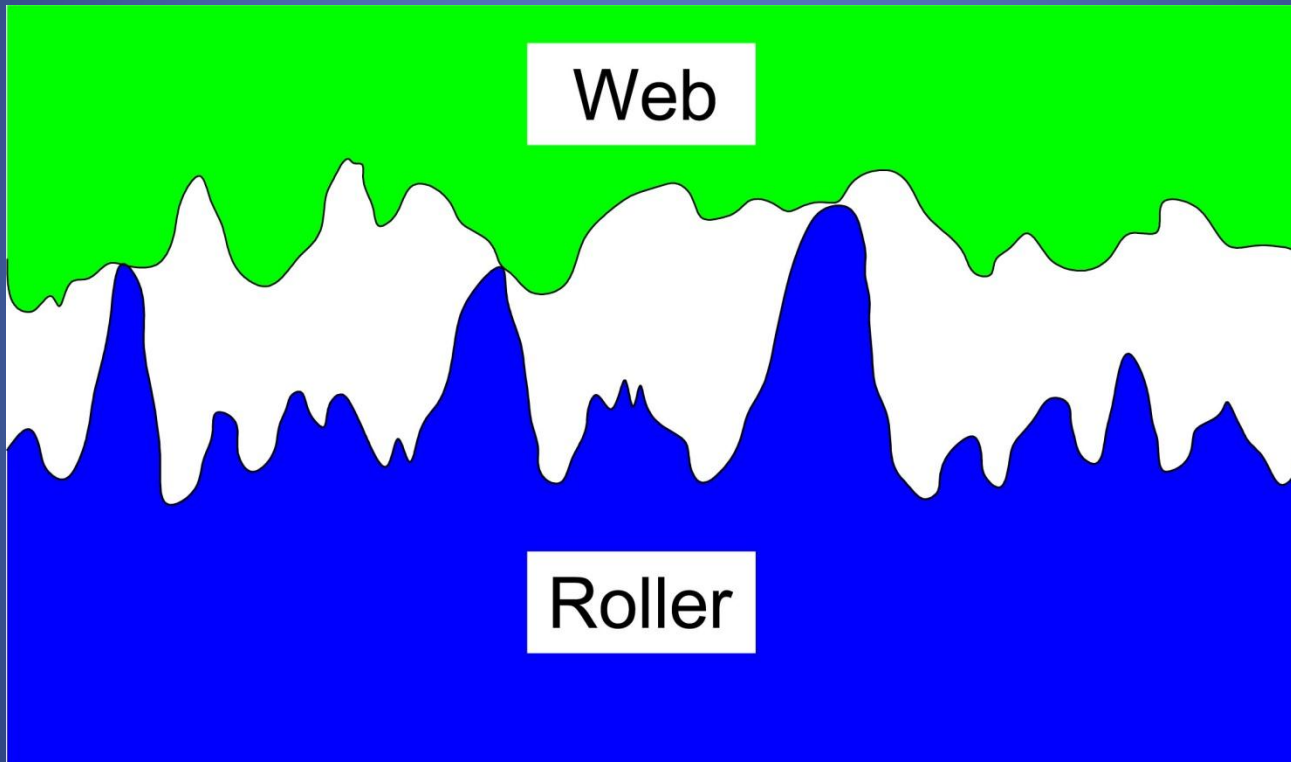
This is evidence of air lubrication.

[Back to friction vs speed](#)

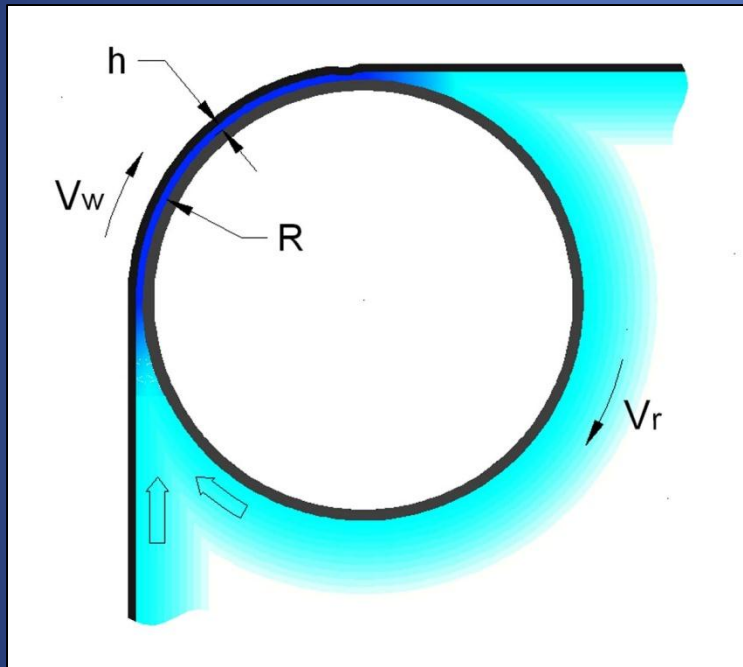
300 ft/min = 1.5 m/s



# Asperities (otherwise known as roughness)



# Air entrainment



$h \uparrow$  as  $R \uparrow$ ,  $V_w \uparrow$  and/or  $V_r \uparrow$ .  
 $h \downarrow$  as tension  $\uparrow$ .

- Air is pumped into gap  $h$  by boundary layers that form on the moving surfaces.
- At low speed, the air flows through spaces created by the asperities.
- As web speed increases, air pressure in the asperity space rises. This opposes the pressure due to tension, which, in turn, reduces friction.
- At some speed, the air pressure will become high enough that the web will completely lose contact with the roller.
- Except for a small dip near the exit and narrow zones at the edges, the effective thickness of the entrained air film is nearly constant over the entire angle or wrap.
- Increasing the roughness of the roller surface allows the web to maintain contact at higher speeds.

# The foil bearing equation

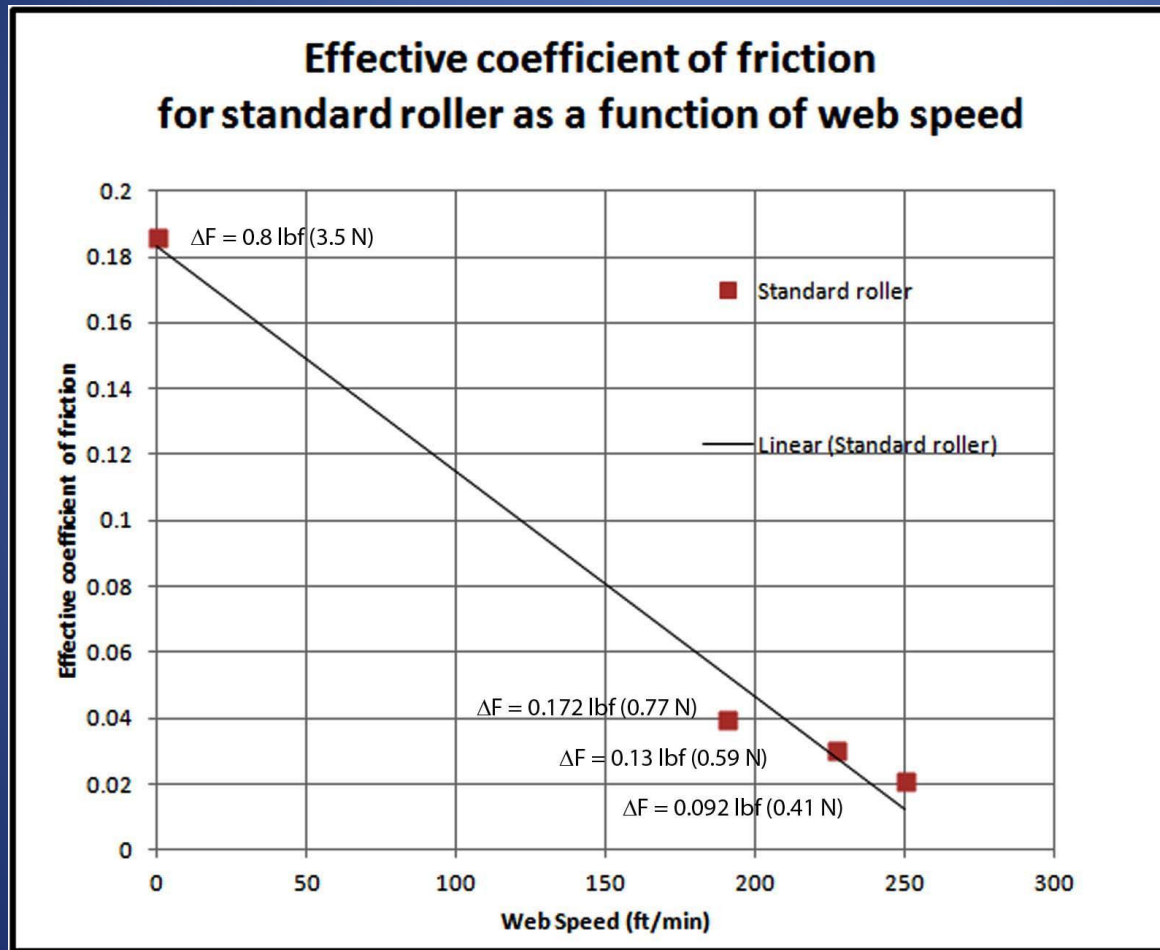
- If a web is nonporous, the effective thickness of the entrained air film,  $h$ , can be calculated using the foil bearing equation (sometimes known as the Knox-Sweeney equation).
  - $R$  = roller radius
  - $V$  = the web speed
  - $T_w$  = the nominal web tension (in units of force per unit of web width)
  - $\mu$  = the viscosity of air
- Centripetal force must also be taken into account. This is usually done by modifying the tension term.
  - $d$  = web thickness
  - $\rho$  = web density

$$h = 0.643R \left( \frac{6\mu(V_w + V_r)}{T} \right)^{\frac{2}{3}}$$

$$T = T_w - d\rho V_w^2$$

# Putting it all together

## The friction curve

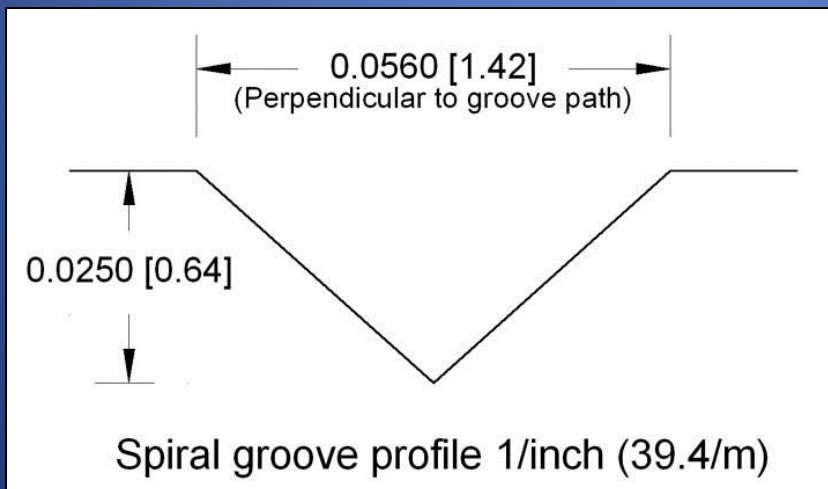
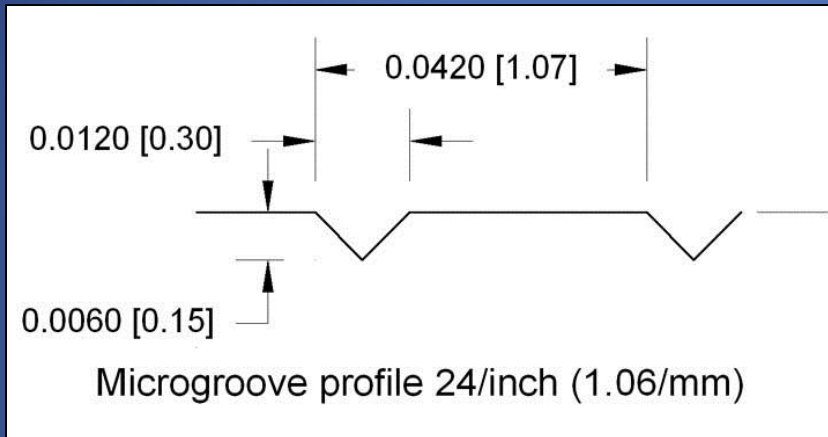


When the web slips, the angle  $\theta$  in the [capstan equation](#) is equal to the wrap angle. So, if we know the entering and exiting tensions it is possible to use [slip curves](#) to calculate the effective coefficient of friction.

# So, what do you lose when it slips?

- The normal entry rule no longer works. This has two important consequences.
  - First, (the bad news) the web's location on the roller is no longer determined by its angle of entry. So, its lateral position will be unstable, changing with tension and other things.
  - Second, (the good news) it will be harder for wrinkles to form because the normal entry effect is an important factor in turning troughs into wrinkles.
- The web may be scratched.

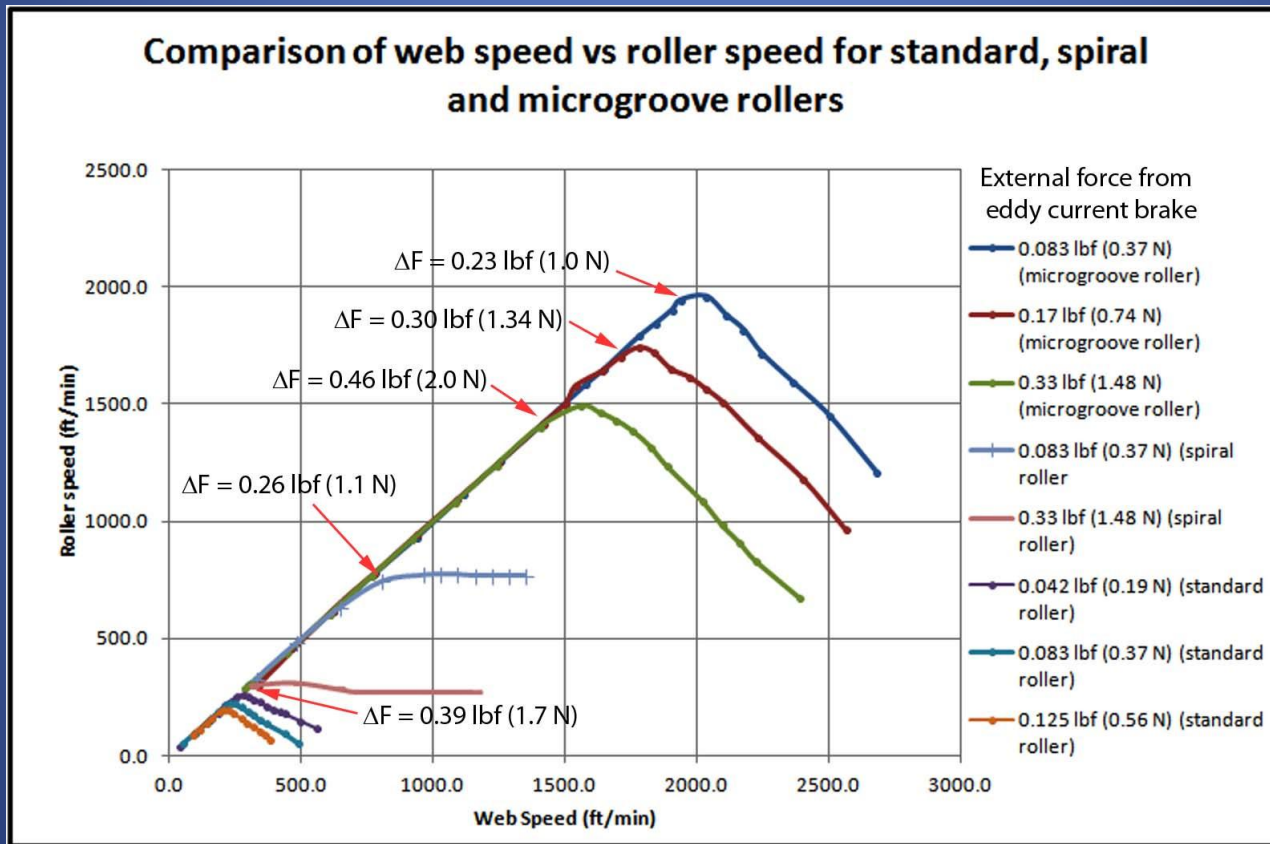
# What to do about slipping



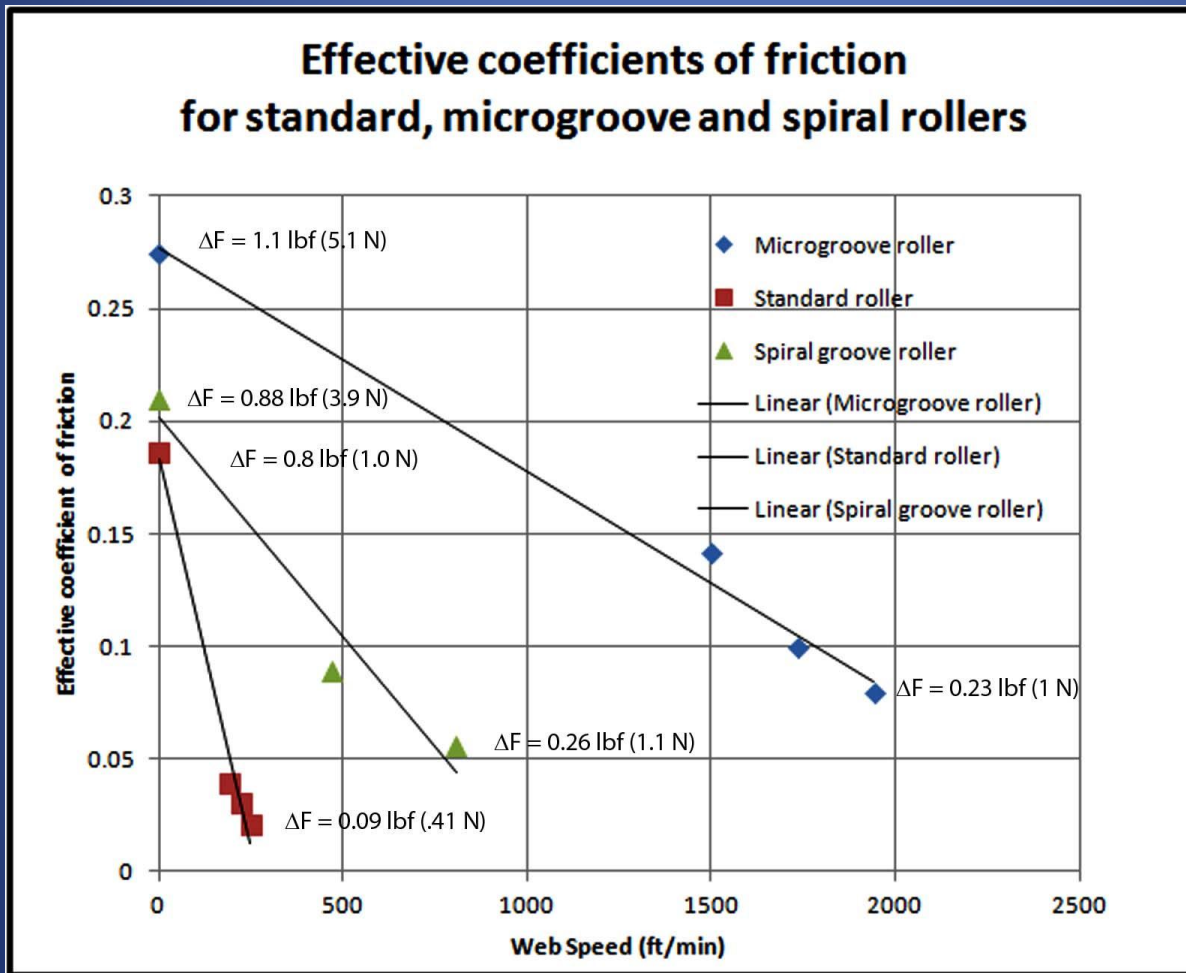
- Make the roller surface rougher (bigger asperities).
- Create artificial asperities (grooves).

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# Comparison of the three rollers



# Comparison of friction curves for the three rollers

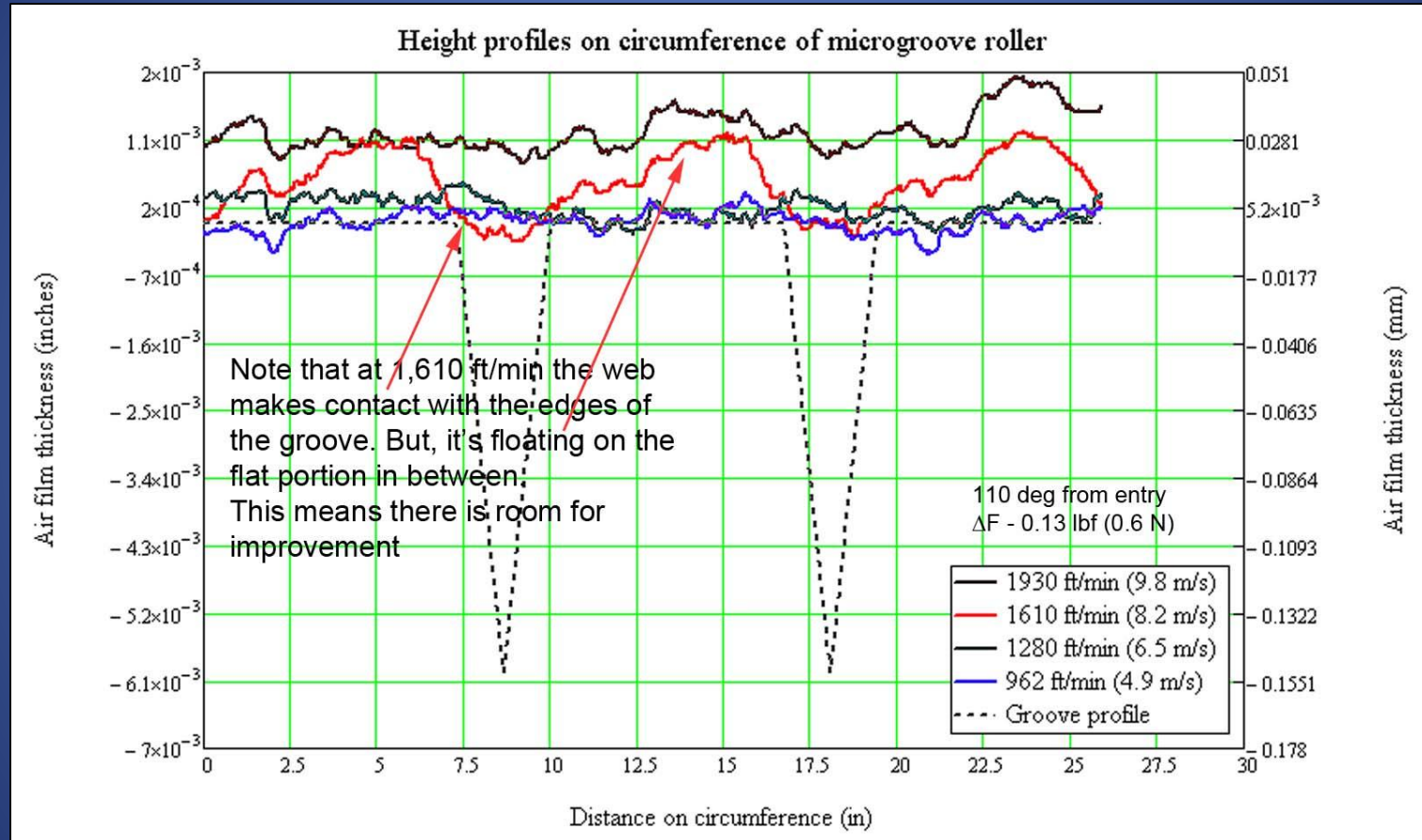


The microgroove roller clearly provides a big improvement in traction.

And, surprisingly, even the spiral groove is an improvement over a typical ungrooved roller.



# Air gap profile on microgroove roller



[Groove geometries](#)

# Summary

- The purpose of the foregoing data is only to illustrate “how things go”. Results will be different depending on just about everything.
  - Roller diameter
  - Tension
  - Bearing drag
  - Web material and roller surface finish
  - Grooving pattern

# If you want to learn more

- Dobbs, J. N., Kedl, D. M. "Measurement and Modeling of Bearing Drag in Idler Rollers", Proceedings of the Fourth International Conference on Web Handling, June, 1997, pp 559-571
- Jones, D. P., "Traction in Web Handling: A Review", Proceedings of the Sixth International Conference on Web Handling, June 2001, pp 187-210
- Roisum, D. R., "The Mechanics of Rollers", Tappi Press, 1996, pp 58, 110
- Ducotey, K. S., "Good, J. K., Predicting Traction in Web Handling", Transactions of ASME, July 1999, Vol 121, pp 618-624
- Rice, B. S., Gans, "A Two-Dimensional Model to Predict Web-to-Roller Traction at Small Wrap Angles", Proceedings of the Seventh International Conference on Web Handling, June 2003, pp 223-273
- Rice, B. S., "Reduction in Web to Roller Traction as a Result of Air Lubrication", PhD Dissertation, University of Rochester, 2003

# Thank you

## Questions?